

Collaboration in social networks: Incentives and topology

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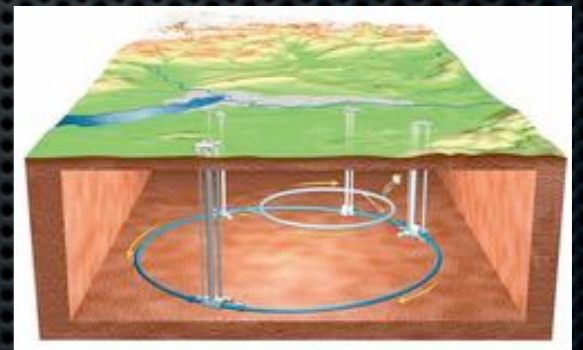
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The puzzle of cooperation

- ✦ Why do we see so much cooperation around?
- ✦ Failed states, why do societies collapse?
- ✦ Will Euro collapse if Greece drops out?



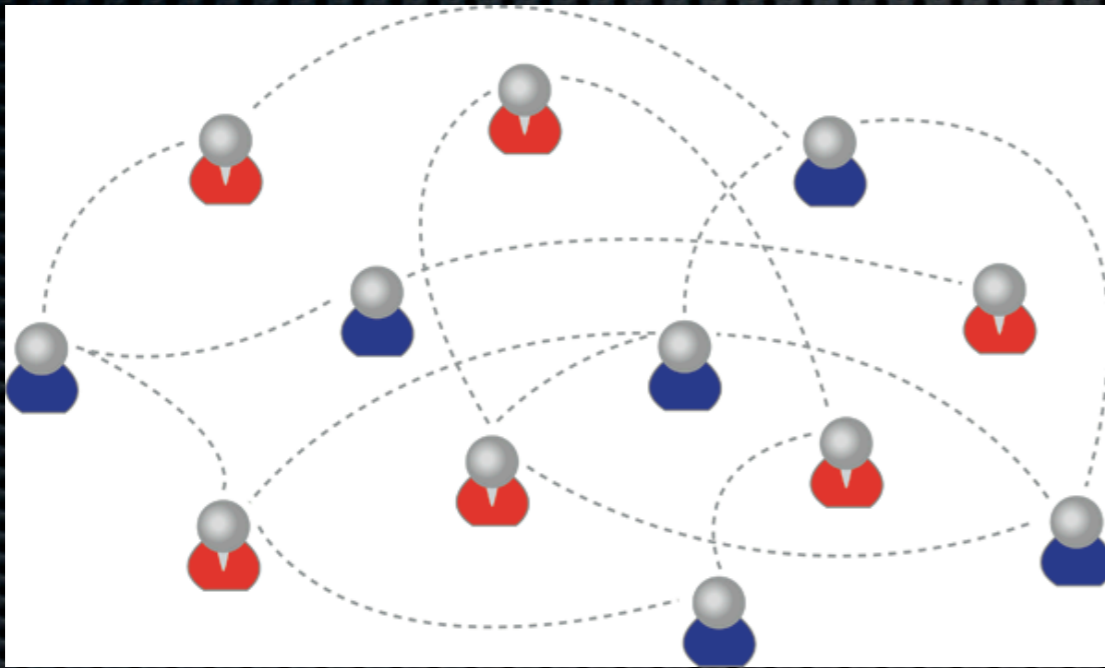
Much has been written on the emergence of cooperation on networks

- Repeated games, reputation and trust (Myerson 1991)
- Endogenous network games (Vega-Redondo 2007, Jackson 2008, Goyal 2009)
- Repeated games on evolving networks (Ellison 1994, Haag Lagunoff 2006, Vega-Redondo 2006).
- Cooperation in evolutionary games without mutation (Boyd 1999, Hofbauer Sigmund 2003, Poncela et al 2010)
- Repeated games and punishment on specific structures (Eshel et al 1998, Haag Lagunoff 2007, Fainmesser 2009, Karlan et al 2009)
- Focus here: social network = pattern of repeated interactions
repeated interaction = forward looking behavior
collaboration = incentives + credibility of threats
How difficult is this in large games on complex structures?

Outline

- The prisoners dilemma
- Collaboration in repeated interaction: 2 players
 - Collaboration is supported by credible threats of punishment
- Collaboration in N players games on a network: Local contribution game
 - Conditional collaboration has to be reciprocal and limited to a subset of neighbors
- How does collaboration depend on incentives and topology?
 - Collaborative equilibria are subgraphs of the social network
- The complexity of collaboration:
 - Counting collaborative equilibria with message passing
- Conclusions

Defection is the only possible outcome in one shot prisoner's dilemma



	C (s=1)	D (s=0)
C (s=1)	1-x, 1-x	-x, 1
D (s=0)	1, -x	0, 0

N players on graph $G=(N,L)$
 Each player either cooperates (C) or defects (D) with all neighbors

Payoff: 1 for each neighbor that collaborates minus X_i (=cost of collaboration)

$$u_i(s_i, s_{-i}) = -X_i s_i + \sum_{j \in \partial_i} s_j$$

All D ($s_i=0$) is the only Nash equilibrium

$$s_i = 0, 1$$

N=2: When the game is played many times cooperation is possible, among other things

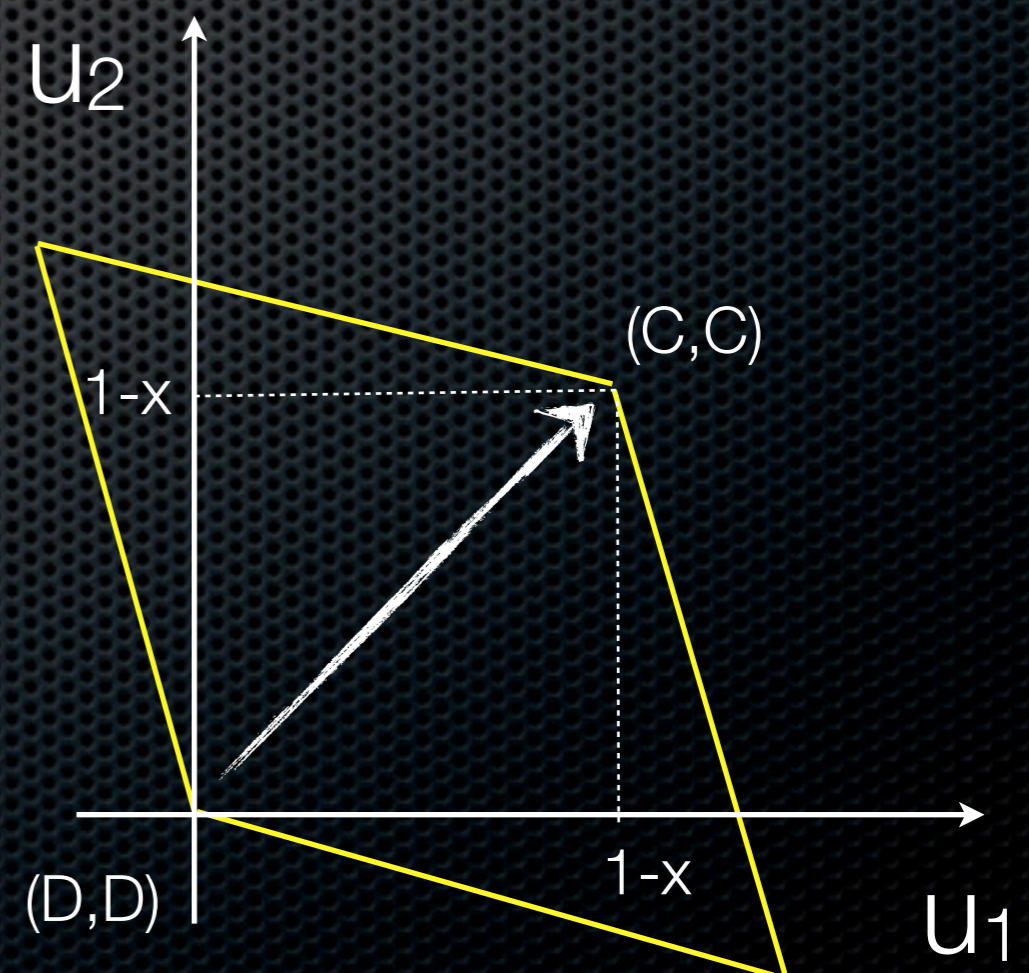
- Strategies become plans of actions, decided at time 0, to optimize future payoffs

$$U_i = (1 - d) \sum_{t=0}^{\infty} d^t u_i \left(s_i^{(t)}, s_{-i}^{(t)} \right), \quad d \in [0, 1]$$

- Cooperation under trigger strategies T:
T = {start with C;
C as long as opponent plays C,
D forever, if opponent plays D}

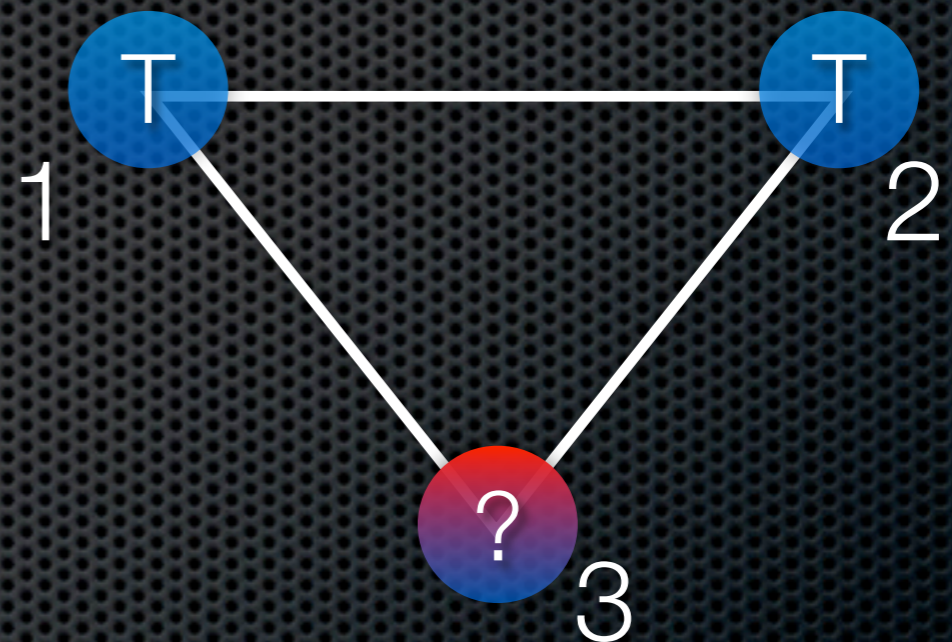
If d is large enough, (T, T) is a Nash equilibrium

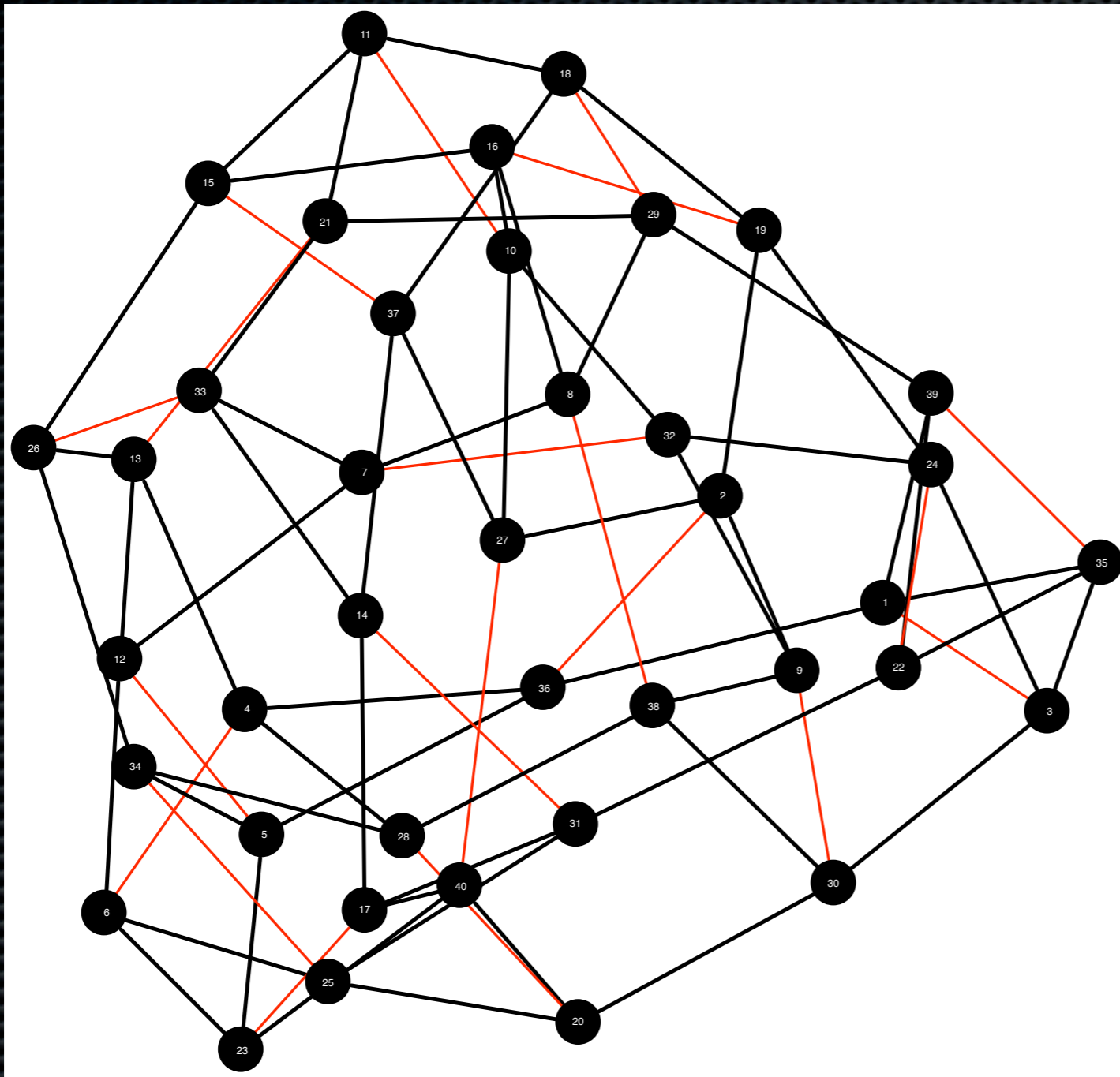
- Folk's theorem: many other outcomes can be supported as a Nash equilibrium
- ! $d=1$ in what follows



But threats should be credible

- $N=3$
- Is it credible that 1 and 2 punish 3?
- Not if $u_1(C,C,D) > u_1(D,D,D)$!
- Players need to condition C only to a subset of their neighbors
- If i conditions on j, j should condition on i
- Emergent heterogeneity



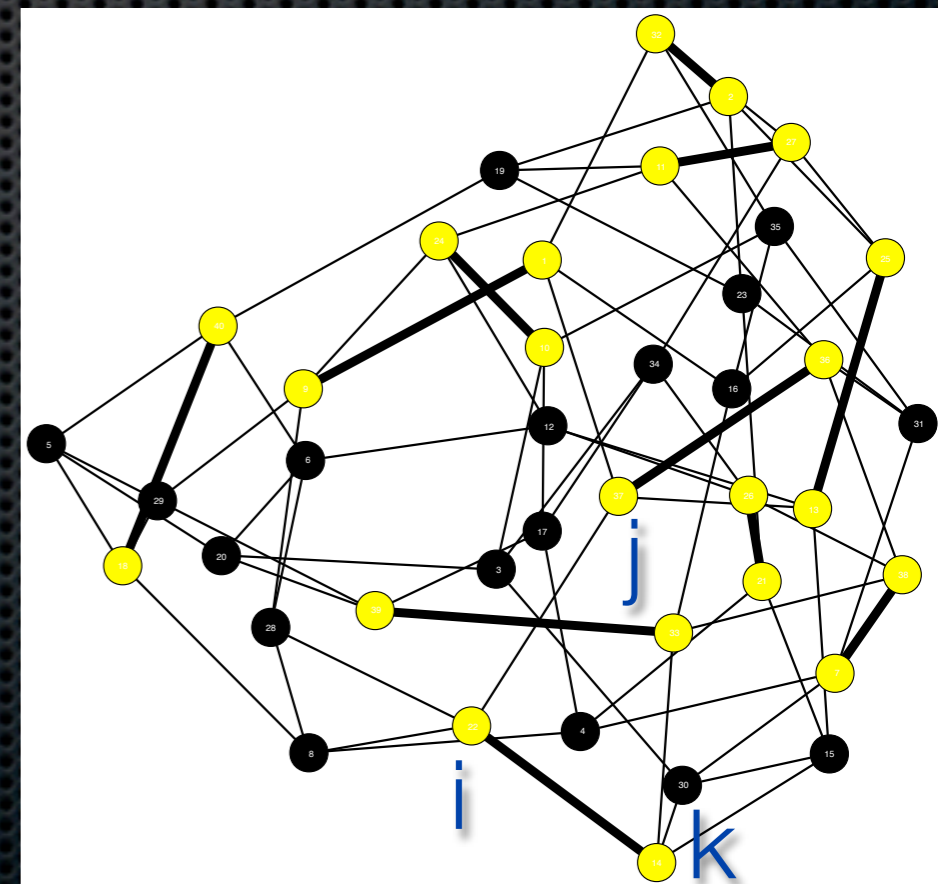


- Trees
- Graphs

On trees, Nash equilibria are subtrees

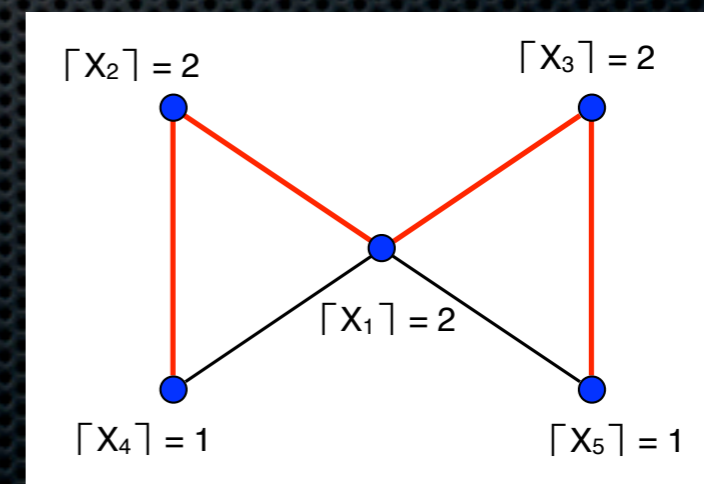
- Given an undirected tree $G=(N,L)$
 - $k_i = |\partial_i| =$ degree of node i
 - $m_i =$ smallest integer larger than X_i
 - $c_i =$ number of collaborators in ∂_i
- Any collection of disjoint undirected subgraphs $\Gamma=(V,\Lambda)$ of G is a collaborative equilibrium where all $i \in V$ cooperate conditionally to neighbors in Γ and $|\partial_i \cap \Lambda|=m_i$
- Incentives: $i \in V \quad c_i - X_i \geq c_i - m_i \Rightarrow m_i \geq X_i$
- Reciprocity: $i, j \in V$, if j does not punish $i \Rightarrow i$ should not punish j when j defects
- Credibility:
 - $i, k \in V, (i, k) \in \Lambda$ if k defects $c_i - 1 - X_i < c_i - m_i \Rightarrow m_i < X_i + 1$

$$u_i(s_i, s_{-i}) = c_i - X_i s_i$$



On generic graphs cascades of defection make things more complex

- Indirect defections: As a result of the defection of $j \in \partial_i$ other neighbors $k \in \partial_i$ may also defect because of loops
- A collection of disjoint undirected subgraphs $\Gamma = (V, \Lambda)$ of G is a collaborative equilibrium where all $i \in V$ cooperate conditionally to neighbors in Γ and $|\partial_i \cap \Lambda| = m_i$ provided
 - i) the indirect effects caused by the defection of all $j \in \partial_i \cap \Lambda$ have the same consequence of the defection of i itself.
- i) holds provided removing i from V does not disconnect Γ
 - Works on trees, for dimers and loops, for the complete graph
 - Likely works on random graphs and on dense graphs



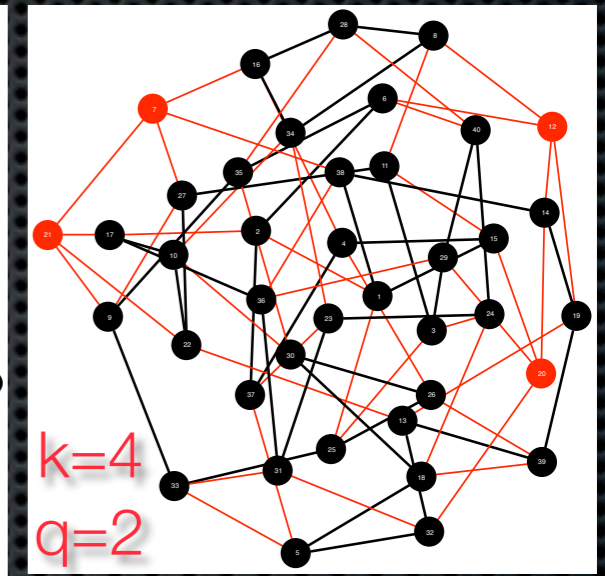
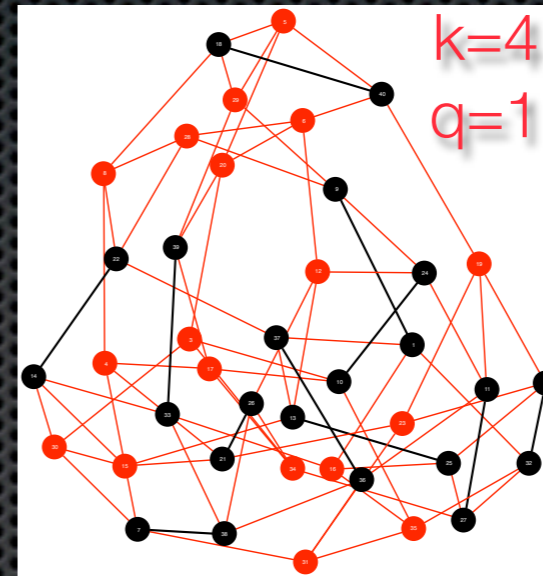
counter example

Nash equilibria on random graphs

Regular random graphs:

$k_i=k$, $X_i=X$ for all i

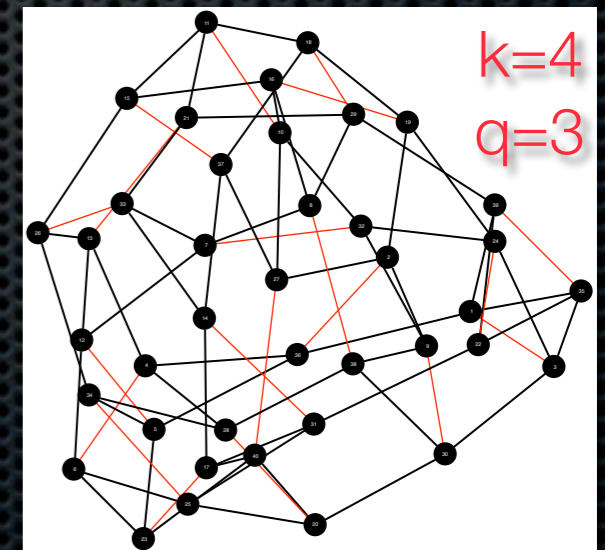
- $X \leq 1$ dimers
- $1 < X \leq 2$ circuits
- ...



$q-1 < X \leq q$ q -regular subgraphs

...

$k-1 < X \leq k$ back to dimers



- Do NE exist? How many? How hard is it to find them?

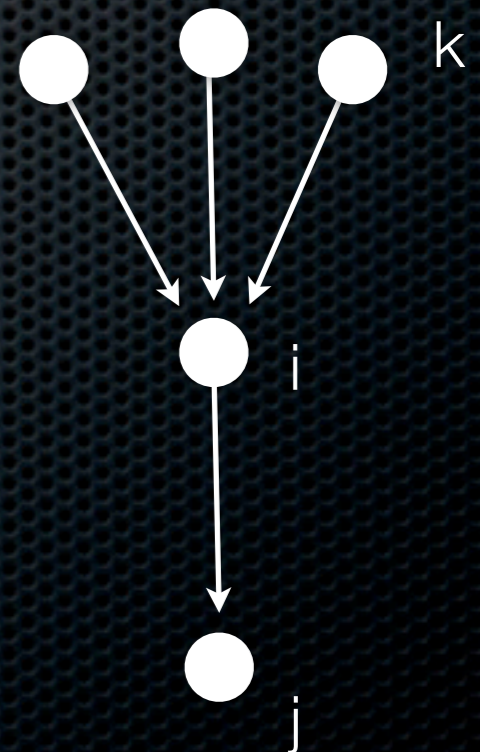
Circuits: Marinari, Monasson, Semerjian 2006
q-regular subgraphs: Prettì, Weigt 2006

Counting NE by message passing

- $x_{i \rightarrow j} = 1$ if i conditions C on j , $x_{i \rightarrow j} = 0$ otherwise
 - there are $m_i - 1$ $k \in \partial_i / j$ with $x_{k \rightarrow i} = 1 \Rightarrow x_{i \rightarrow j} = 1$
 - m_i $k \in \partial_i / j$ with $x_{k \rightarrow i} = 1 \Rightarrow x_{i \rightarrow j} = 0$
 - no $k \in \partial_i / j$ with $x_{k \rightarrow i} = 1 \Rightarrow x_{i \rightarrow j} = 0$

- Marginals:

$$\mu_{i \rightarrow j} = P\{i \in V, i \text{ punishes } j\}$$



Circuits: Marinari, Monasson, Semerjian 2006
q-regular subgraphs: Pretti, Weigt 2006

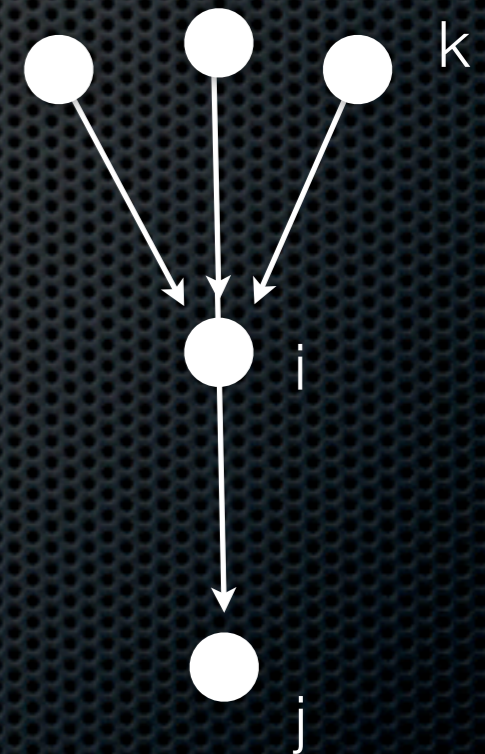
Message passing equations:

$$\mu_{i \rightarrow j} = \frac{e^{-\epsilon} Z_{N_i \setminus j \rightarrow i}^{m_i - 1}}{Z_{N_i \setminus j \rightarrow i}^0 + e^{-\epsilon} Z_{N_i \setminus j \rightarrow i}^{m_i - 1} + e^{-\epsilon} Z_{N_i \setminus j \rightarrow i}^{m_i}}$$

$$Z_{V \rightarrow i}^q = \sum_{U \subseteq V} \mathbb{I}_{|U|=q} \prod_{j \in U} \mu_{j \rightarrow i} \prod_{k \in V/U} (1 - \mu_{k \rightarrow i})$$

$$P\{i \in C\} = \frac{e^{-\epsilon} Z_{N_i \rightarrow i}^{\gamma_i}}{Z_{N_i \rightarrow i}^0 + e^{-\epsilon} Z_{N_i \rightarrow i}^{\gamma_i}}$$

$$P\{i \in \Gamma_j\} = \frac{\mu_{i \rightarrow j} \mu_{j \rightarrow i}}{\mu_{i \rightarrow j} \mu_{j \rightarrow i} + (1 - \mu_{i \rightarrow j})(1 - \mu_{j \rightarrow i})}$$



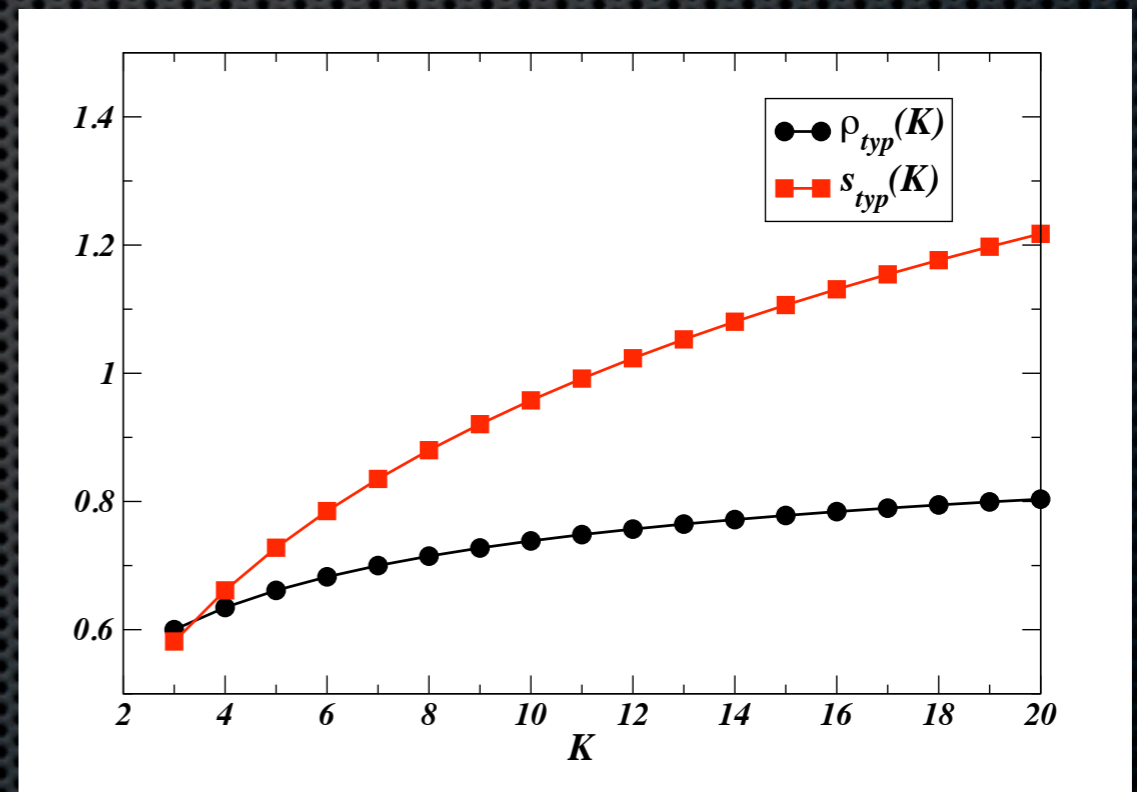
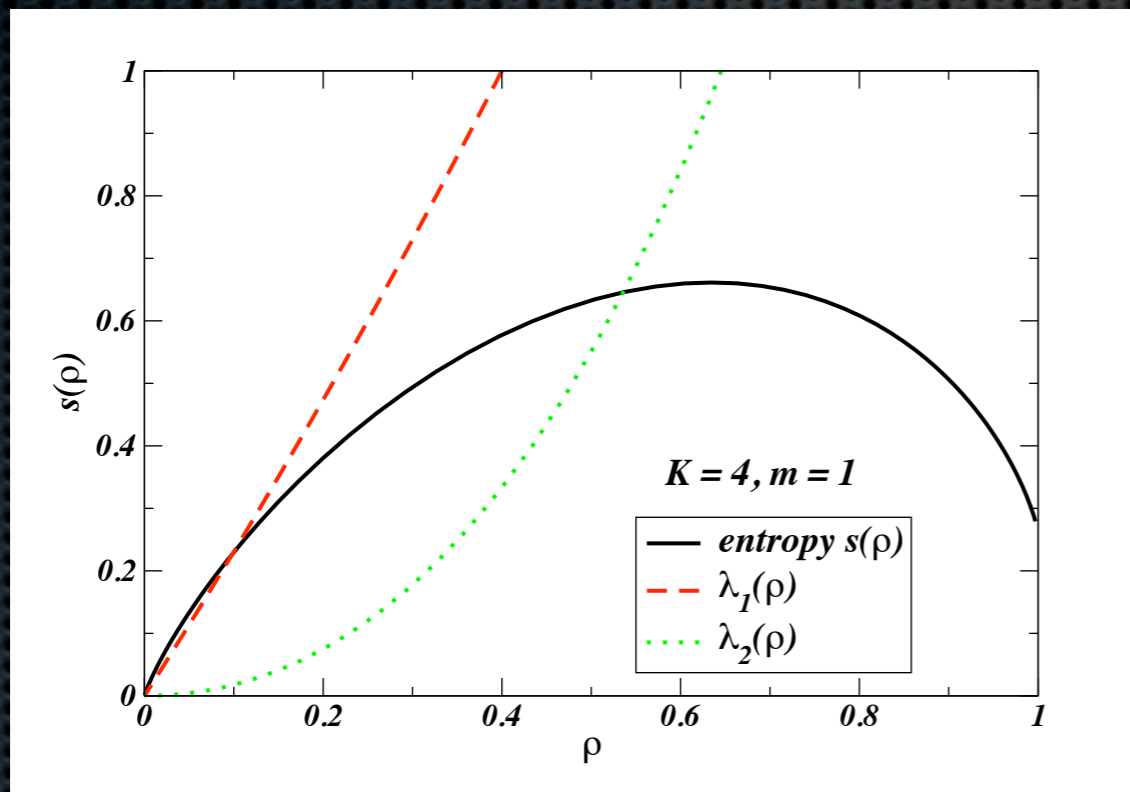
- Fixed point \Rightarrow number of subgraphs (entropy)

Circuits: Marinari, Monasson, Semerjian 2006
 q-regular subgraphs: Pretti, Weigt 2006

Regular random graphs: dimers

($m_i=1$)

- Exponentially many NE's



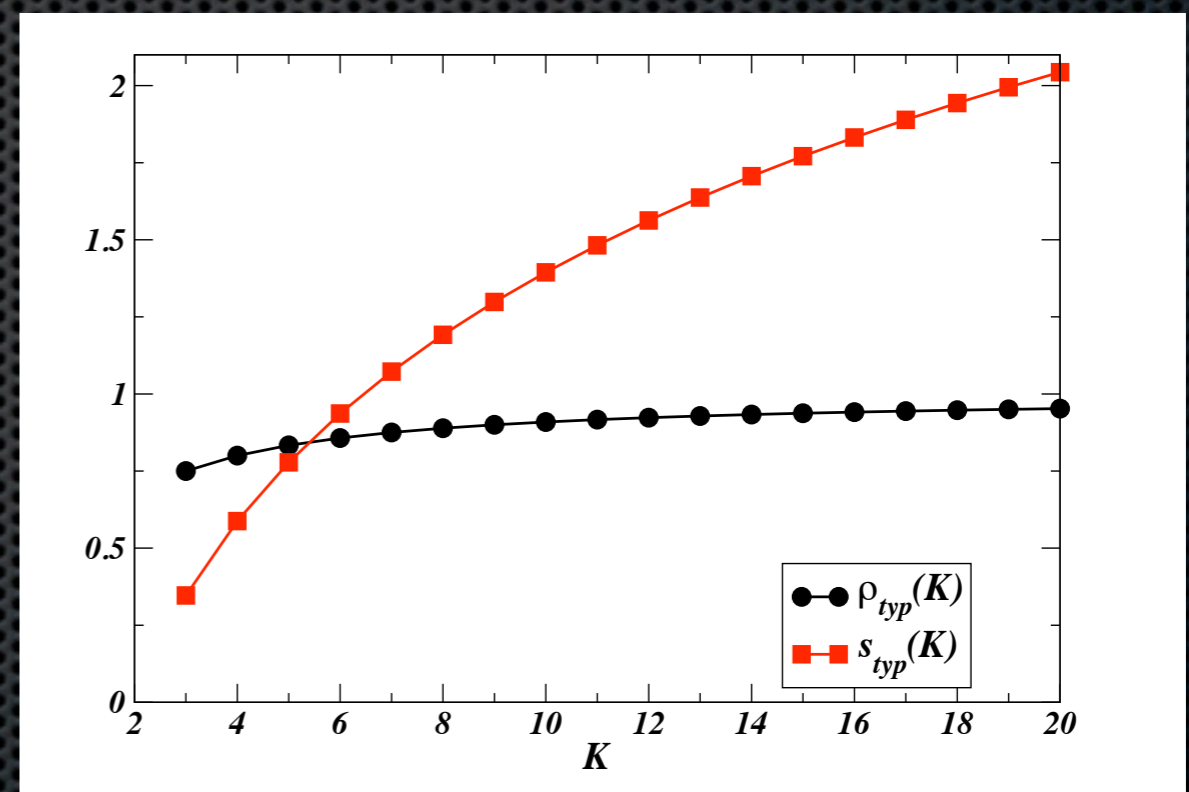
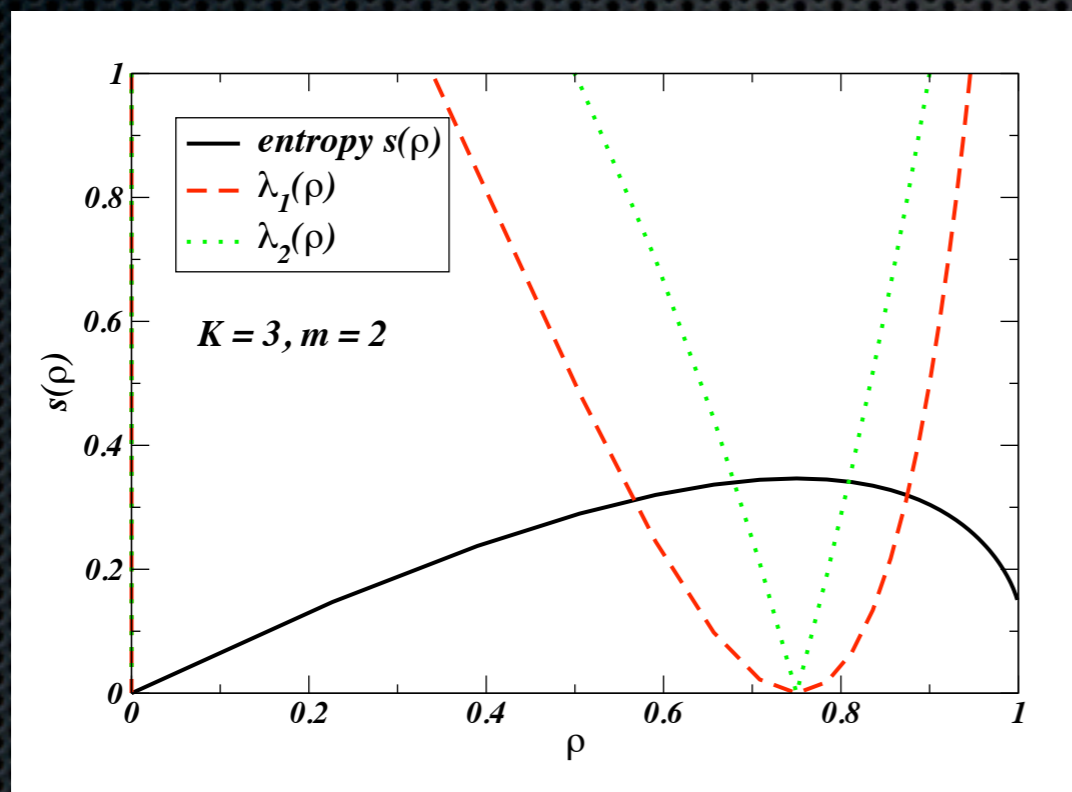
- ρ = fraction of cooperators
 $s(\rho) = \log(\text{number of NE}|\rho)/N$

$$\text{NE} \exists \forall \rho \in [0, 1]$$

Regular random graphs: circuits

($m_i=2$)

- Exponentially many NE's

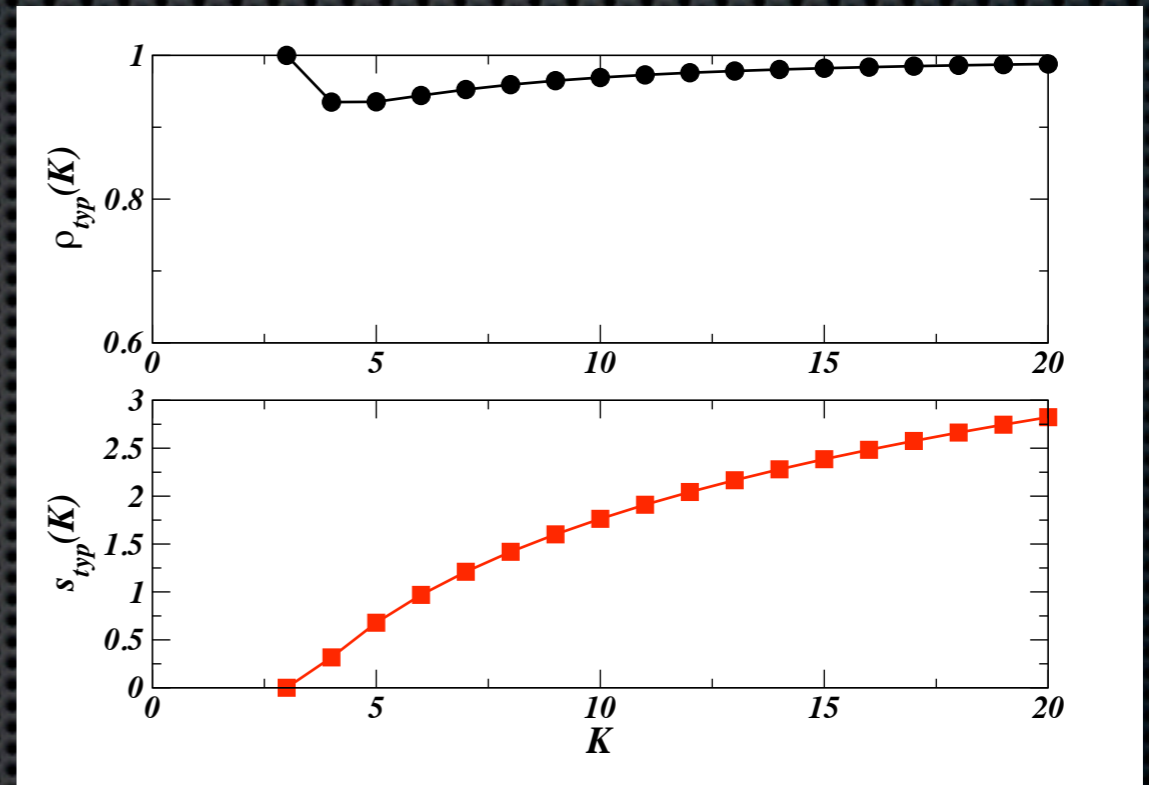
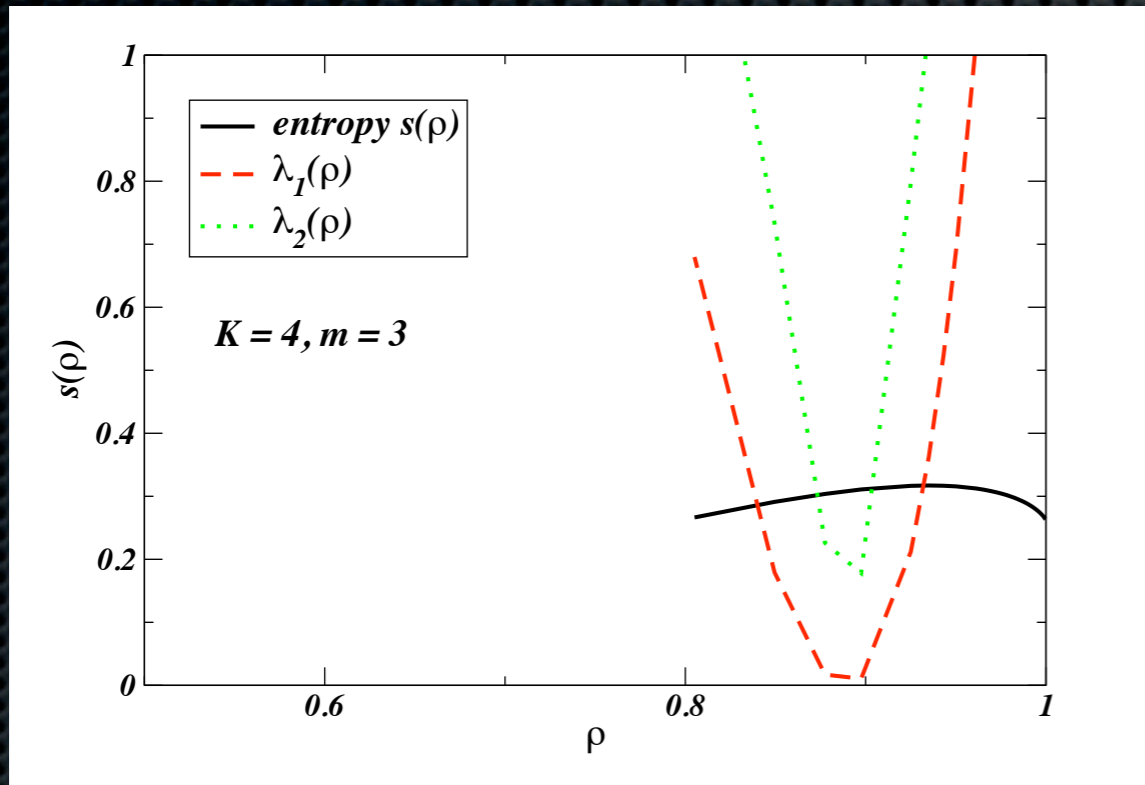


- ρ = fraction of cooperators
 $s(\rho) = \log(\text{number of NE}|\rho)/N$

$$NE \exists \forall \rho \in [0, 1]$$

(Marinari, Monasson, Semerjian 2006)

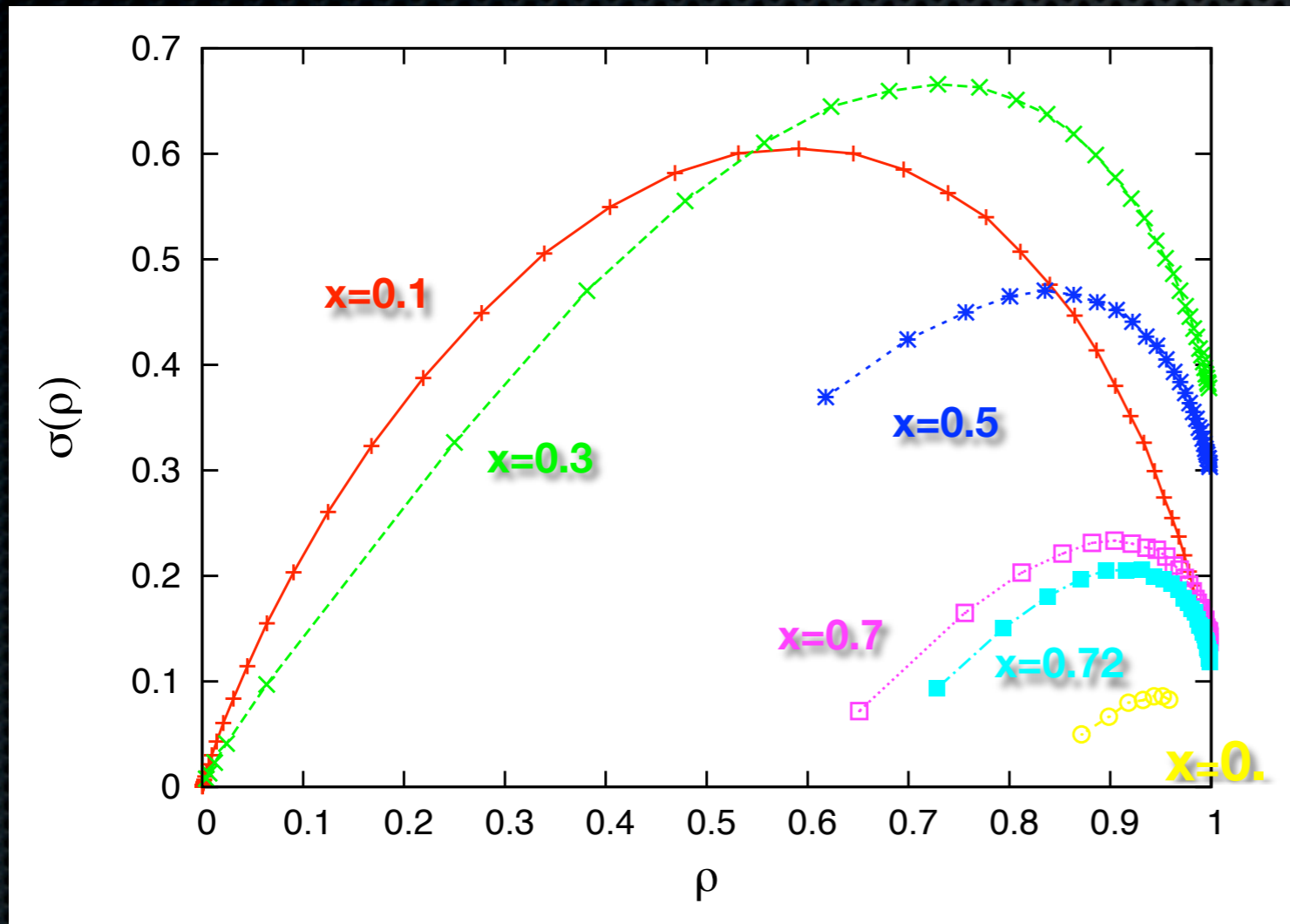
Regular random graphs: $m_i=3$



- ✦ Exponentially many NE's
- ✦ $NE \nexists \forall \rho < \rho_c$
- ✦ NE are non-local and fragile

(Pretti, Weigt 2006)

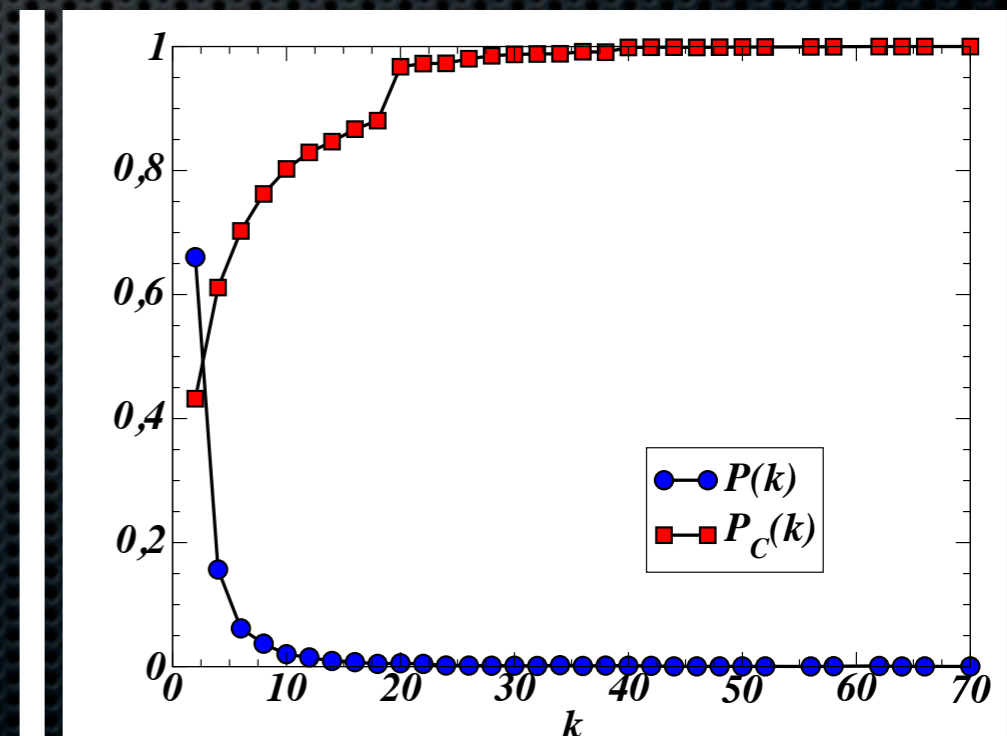
Heterogeneous random graphs



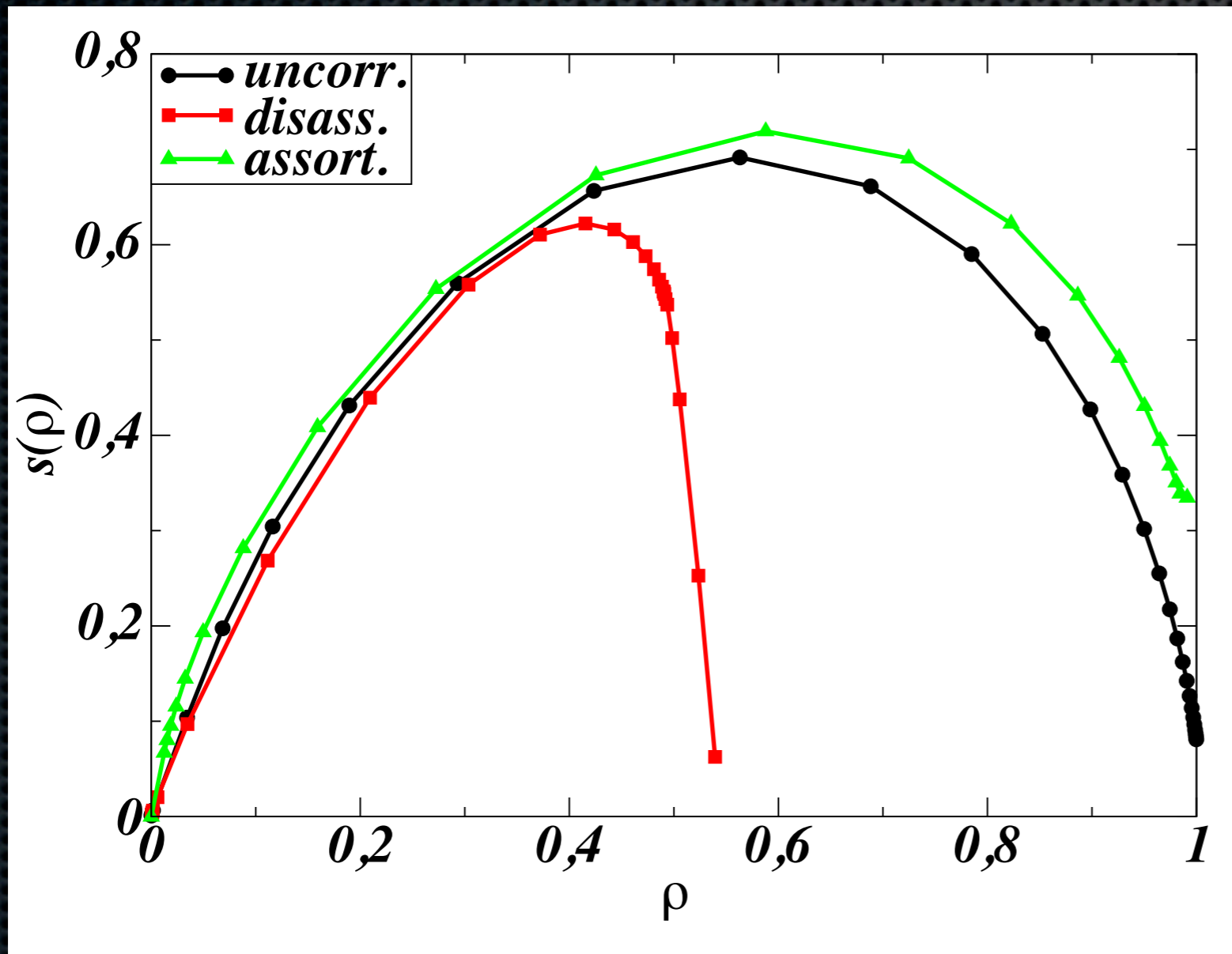
Erdős-Rényi: $E[k]=4$

$$X_i = xk_i$$

Scale free: hubs collaborate more likely than spokes



Assortative networks are more conducive to collaboration



Scale free network
 $P(k) \sim k^{-2.5}$
 $X_i = xk_i, x=0.1$

Conclusions: Theory

- Collaboration in repeated prisoners dilemma as a graph theoretical problem:
 - 1- make sure enough neighbors collaborate
 - 2- not credible to monitor more neighbors
 - 3- checks should be reciprocal
- If incentives to defect (x)
 - is small then cooperation is easy
 - is large
 - i) collaboration requires critical mass
 - ii) Nash equilibria are fragile
 - iii) effect of defection are non-local
- Topology: Collaboration is easier on
 - i) trees
 - ii) densely connected graphsCollaboration is harder on networks which can be disconnected (e.g. quasi 1d graphs)

Conclusion: Empirical evidence

- Individuals condition collaboration on that of others (Fishbacher, Gächter, Fehr 2001)
- Weak and strong ties (Granovetter, 1973)
Individuals do not condition collaboration to all contacts, not even to all those who collaborate, only to a subset of them
- Critical mass theory of collective action (Oliver, Marwell 1993)
If the cost of collaboration is large enough, collaborative equilibria only arise if a finite fraction of agents participate
- Collaboration easier in dense networks (Kirchkamp, Nagel 2007; Cassar 2007)
- More connected agents are more likely to collaborate (Cassar 2007)
- Collaboration is not contagious (Suri, Watts 2011)
The more of my contacts are engaged in conditional collaboration with others, the less likely I am to find neighbors with whom to collaborate conditionally